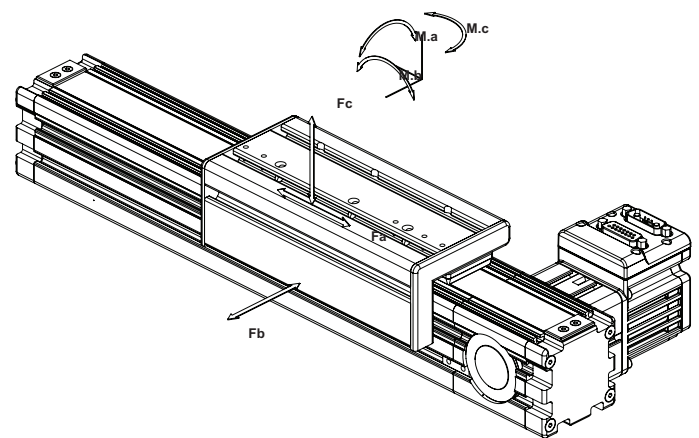
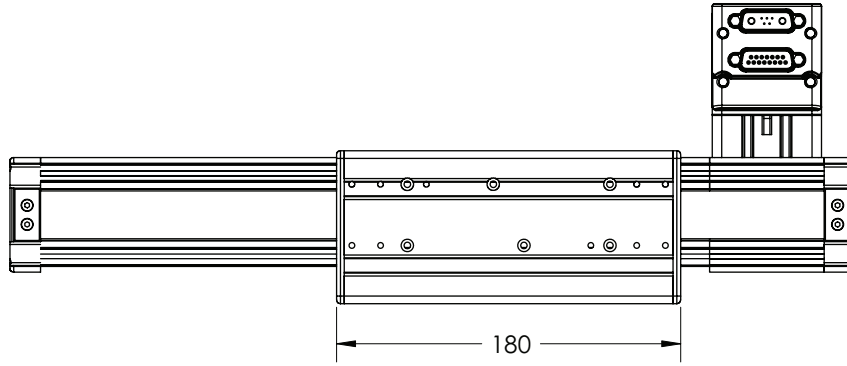


HLD60 with Internal Roller Specifications

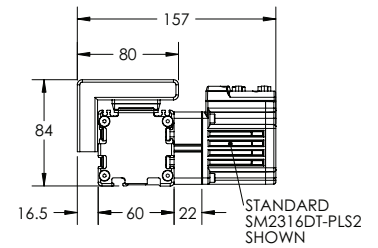
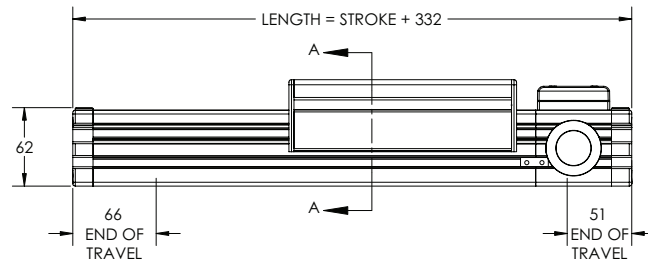
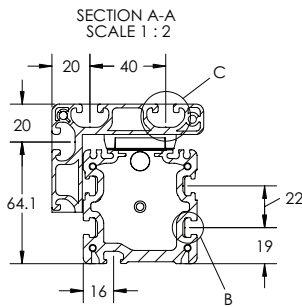


Parameter	Value				Units
Configuration & Physical Parameters					
Motor	Animatics Size 23 Motors				-
Coupling	Flexible Jaw				-
Displacement/rev	2.5, 5, 10, 12.5				mm/rev
Position sensors	Optional Home & EOT limits				-
Stroke	100-600mm in 50mm steps 600-1000mm in 100mm steps 1000-3200mm in 200mm steps Custom lengths are available				mm
Overall length (L)	Stroke + 332				mm
Over-travel	25				mm
Unit mass	2.3 + 0.0031 x (stroke, mm) + (motor mass, kg)				kg
Performance					
Unidirectional repeatability	<20				µm
Bi-directional repeatability	60-180 (belt tension dependent)				µm
Accuracy *	0.5 per 300 stroke				mm/mm
Displacement/rev	2.5	5	10	12.5	mm/rev
Linear speed @ 4200RPM	175	350	700	875	mm/s
Payload Mass**	45	42	18	13	kg
Continuous Thrust (Fa)					
SM2315D @ 48V @ 4500RPM	115	40	-	-	N
SM2315DT @ 48V @ 3300RPM	450	245	100	70	N
SM23165D @ 48V @ 4500RPM	270	120	35	-	N
SM23165DT @ 48V @ 3800RPM	450	420	185	135	N
SM23375D @ 48V @ 4500RPM	175	70	10	-	N
SM23375DT @ 48V @ 3200 RPM	450	290	125	90	N
Load Rating, Dynamic ** (Static)					
Fb	56 (110)	44 (110)	35 (110)	33 (110)	N
Fc	56 (200)	44 (200)	35 (200)	33 (200)	N
Carriage moments, Dynamic ** (Static)					
M.a	1.0 (2.4)	0.8 (2.4)	0.6 (2.4)	0.55 (2.4)	Nm
M.b	3.2 (8)	2.5 (8)	2.0 (8)	1.9 (8)	Nm
M.c	3.2 (12)	2.5 (12)	2.0 (12)	1.9 (12)	Nm

*Consult factory if greater accuracy is required
 **Based on a 15000HR service life
 @ 75/150/300 & 375mm/s (1800 RPM) average speed at given payload
 Subject to routine lubrication
 All OEM Dynamics™ Linear Integrated Systems are covered by
 Animatics patent #5,912,541 and other patents are in progress worldwide



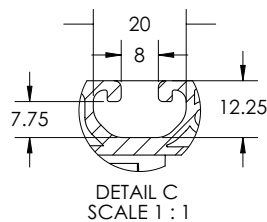
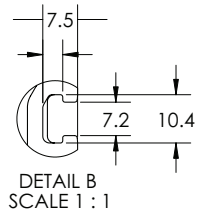
TOP VIEW



SIMPLE END VIEW

RIGHT SIDE VIEW

MOTOR END VIEW



DETAILED END VIEW

Dimensions in millimeters

Note: For part numbers please refer to our Website at www.oemdynamics.com

Thrust Curve performance data in following section on pages 109-126.